001 ..... 1
002 ..... $\cdot 2$
003 ..... - 3
004 ..... - 4
005 ..... 5
006 .....  6
007 ..... 7
008 ..... 8
009 ..... $\cdot 9$


## TETRA-DSV Application hYUl_IM networks



## TETRA-DSV Application HYULIIM NEEWorks



## C-BOX Detail Description hyulim newors



## Wheel Driver Board Power Senser Board

## Front of the TETRA-DS BackLinkBoard

## UART PORT (RS-232C)

(Direct Control using User PC)

4 V INPUT PORT X 8
24 V -OUTPUTPORT X 8
$0 \sim 5 \mathrm{~V}$ ADC PORT X 8

UART PORT (RS-232C)
Wheel Driver POWER SWITCH

## C-BOX Detail Description hyu_IM newwors



Wheel Driver Board
Power Senser Board

## Back of th

23~28V 20A Battery FUS
24V 4A POWER(1)
$\overbrace{\text { EMS Signal PIN }}^{\substack{\text { PUSH LOCK } \\ \equiv>\text { POWER ON }}}$ (Active LOW)


12V/5V 1.5A POWER
12V 4A LiDAR POWER
19V 4A PC POWER
10V 4A POWER



TETRA-US БackLink Rev: (2.01


| 3 -1  <br>  $\theta$ $A$ <br> 0 0 $\theta$ |
| :--- | :--- | :--- |

$\sqrt{6}$


## C-BOX Detail Description hyulim newwors



Wheel Driver Board
Power Senser Board

## Back of the TETRA-DS BacklinkBoard



고정밀 산업용 20:1 감속기

## C-BOX Specifications

## Specifications



## Wis 혁신상

# 과학기술정보통신부장관상 

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TETRN-DEV

